

Procedure for moving a Fanuc robot using the Pendant

- Ensure that the keyswitch is not on auto (located on the control module)
- Ensure that the switch on the top of the pendant is not set to auto (top left of the pendant)
- Lightly squeeze both deadman switches (located on the back of the pendant)
- With your left hand press the shift key (top left of the pendant)
- Then press either: Z(+,-) X(+,-) or Y(+,-) to move the robot into the proper position
- Reset the errors with the pendant by pressing the shift+reset keys

